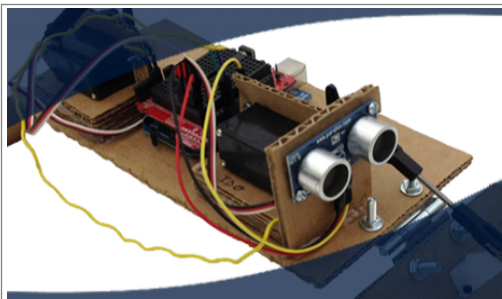


MARCH 18, 2014

Statement of Accomplishment

ROSHENAC MITCHELL

HAS SUCCESSFULLY COMPLETED GEORGIA INSTITUTE OF TECHNOLOGY'S ONLINE OFFERING OF



Control of Mobile Robots

This course investigates control design for mobile robots, including topics such as dynamical systems, state-space based control design, nonlinear and hybrid robot models, and advanced navigation strategies.

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